

# AuScope VLBI Operations Training

Jim Lovell  
Updated 14 Dec 2015

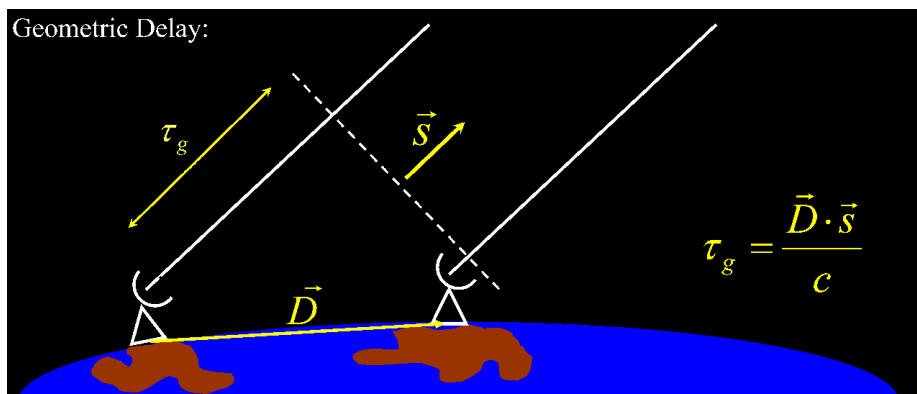
## Program

9.30 – 10.30	Introduction
10.30 – 11.00	Coffee
11.00 – 12.30	Setup and observing procedure.

# Background I

- AuScope is a federally funded infrastructure project: “Structure and Evolution of the Australian Continent”
- Geospatial is a component of AuScope. Investment in:
  - three 12-meter radio telescopes and a software correlator
  - about 100 GPS receivers
  - upgrade of existing SLR facilities
  - an absolute gravimeter and three tidal gravimeters
  - improved computing facilities
- AuScope VLBI : [auscope.phys.utas.edu.au](http://auscope.phys.utas.edu.au)

# What is Geodesy?



- [A Brief History of Geodesy \(NASA GSFC\)](#)

## Background 2: VLBI

- VLBI provides Earth Orientation Parameters (EOP) and ties the inertial Celestial Reference Frame (CRF) to the Terrestrial Reference Frame
- It's the only technique capable of this
- 3 observatories connect new GPS array to the CRF, help address lack of geodetic VLBI sites in the southern hemisphere.
- Built and operated by UTAS



## AuScope VLBI and you

- 7 million dollars
- 4 years
- 3 observatories operated remotely
- 1 person in control..... you

## Appointment policy for casuals

### **Appointment policy for AuScope VLBI Array Operators**

26 Feb 2014

Priority is given to post-graduate students (Masters and PhD candidates) who intend to be at UTAS for at least six months from date of appointment. This provides an additional source of income for students and also gives them valuable training and experience in the use and operation of radio telescopes. The six month requirement exists given the significant amount of training and experience required for a new appointee to become fully competent. Appointments end when the post-graduate student's candidature finishes.

Others with previous experience in radio astronomy, VLBI operations or closely aligned fields (such as spacecraft tracking) will be considered if they have specially needed skills.

All new appointments are initially for a three month probationary period.

It is expected that all operators will make themselves available to support Australian Long Baseline Array (LBA) observations at Mt Pleasant, Ceduna, Katherine and Yarragadee on an unpaid basis.

## Operator Observing shifts

- Experiments usually start ~4 - 5 AM but may be back-to back with other experiments.
- Shift changes at 09.00, 17.00, 23.00 local.
- Schedule prepared by IVS for a full calendar year. Roster done by students (currently Ellen).
- Non-casual staff take care of the day shifts
- You are in charge of the array and the first point of contact during the observations.
- You should be in the control room. It is also possible to run observations from Mt Pleasant if necessary.

## Getting help

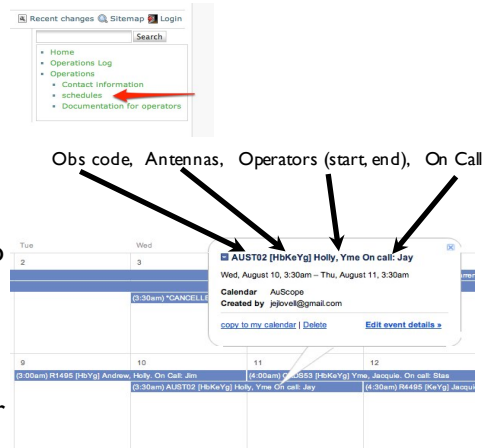
- The Operations Wiki is your friend  
[auscope.phys.utas.edu.au/opswiki](http://auscope.phys.utas.edu.au/opswiki)  
Feel free to add, update, edit & correct  
You'll need an account.
- Nomenclature:
  - Hb = Hobart 12m
  - Ho = Hobart 26m
  - Ke = Katherine 12m
  - Yg = Yarragadee 12m

## Stuff you should be familiar with

- Windows and Linux/UNIX environment
- Linux:
  - vi and emacs editors
  - Unix shell (ls, cd, cp, mv, ps, cat, less, grep, find, kill, df, sed, awk, ssh, sudo)

# Schedules, Rosters

- Available from wiki
- Link to IVS Master schedule
- Google calendar with roster and on-call allocations. You should be able to edit it
- Please advise if you're going to be away, any times you can't observe. There's a calendar and a wiki page for this



# On-call person

- For each experiment, someone is scheduled On Call, the first point of contact if there's a problem you can't solve yourself, or if there's anything you don't understand, doesn't look right etc.
- Currently Jim, Jamie, Warren
- Brett for maser-related issues
- Also someone at Ke, Yg to call on in emergencies. Ke and Yg people also do occasional maintenance, change disk modules etc

# Operations Room

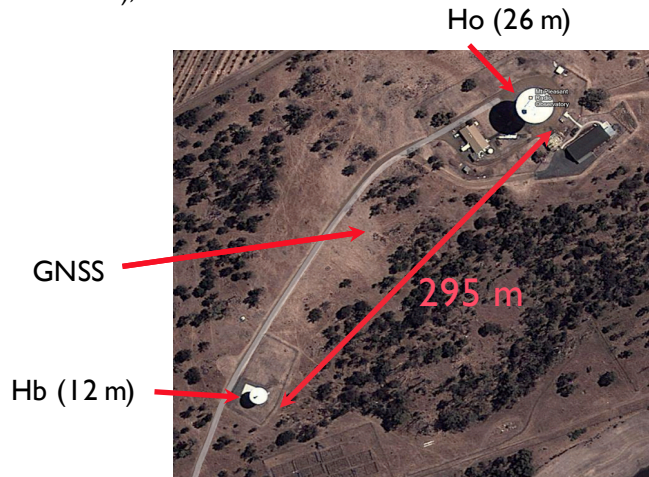
- You'll need a key & after-hours pass
- Main operations PC is ops2 (6-monitor PC)
- Ops4 for other observations, screen space (e.g. Ceduna, Mt Pleasant 26m, 14m) or if ops2 dies
- Also a Windows PC, PCs for status/public display on walls
- ops-serv2 in rack in 'kitchen' (username observer) for admin, serve shared directories etc.
- "Lounge" with PC (ops6) to echo alarms etc.
- Two phones:
  - x2407, "Admin" desk, next to Ops4. Cordless : take it with you.
  - x7528, "Operator" desk, next to Ops2

# Use of Operations Room

- Please keep kitchen area clean
  - Clean coffee machine after use
  - Replace coffee beans when gone
  - BYO
  - Water in tea room downstairs
- "Lounge"
  - If you use the sheets, take them home and wash them after your shift. Or bring a sleeping bag.

# Sites: Hb

- Same location as Ho (Hobart 26m), 20 km from city
- 1 Gbps fiber



GNSS

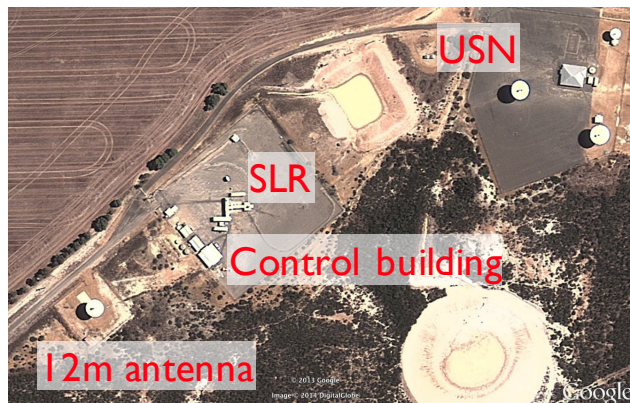
Hb (12 m)

Ho (26 m)

295 m

# Sites: Yg

- Co-located with a Satellite Laser Ranging (SLR) facility, operated 24/7. SLR operator is our local contact
- Co-located with Universal Space Network (USN) and NASA tracking facilities



USN

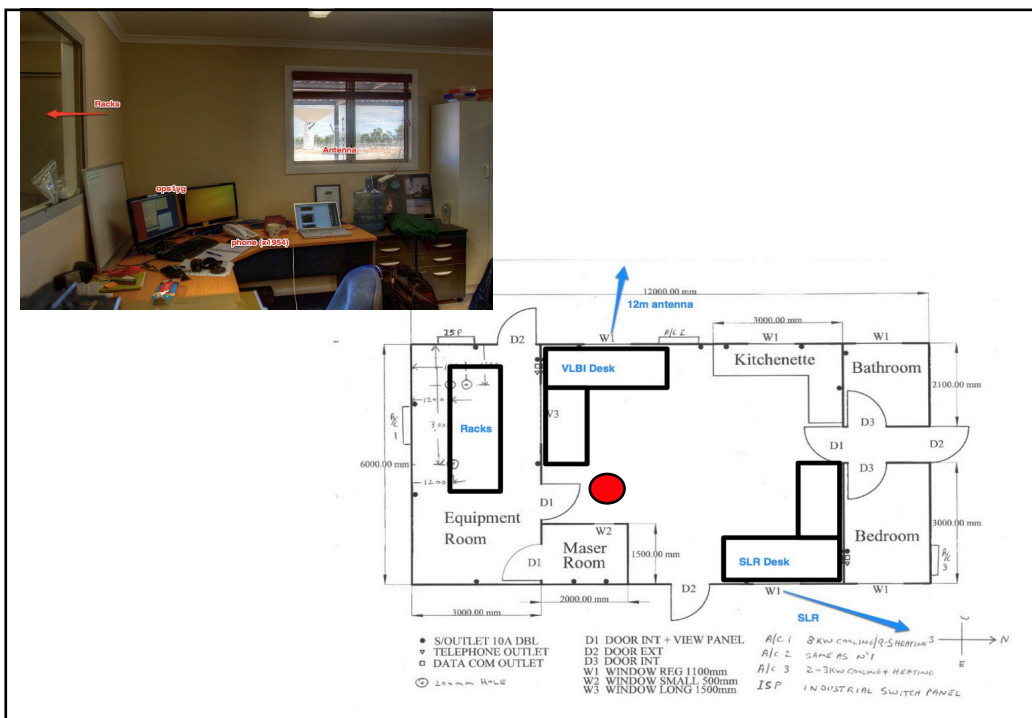
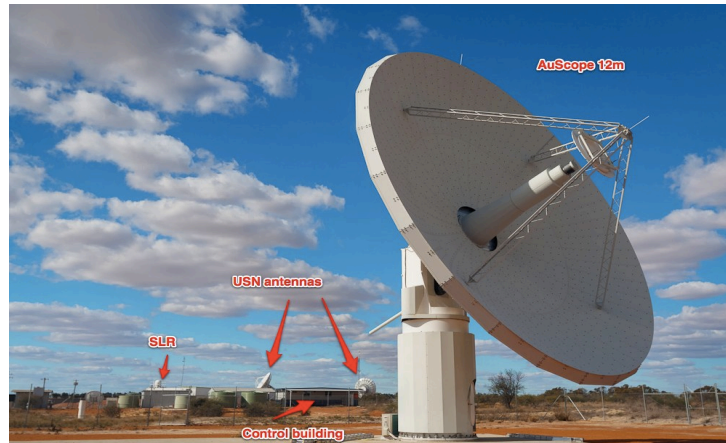
SLR

Control building

12m antenna

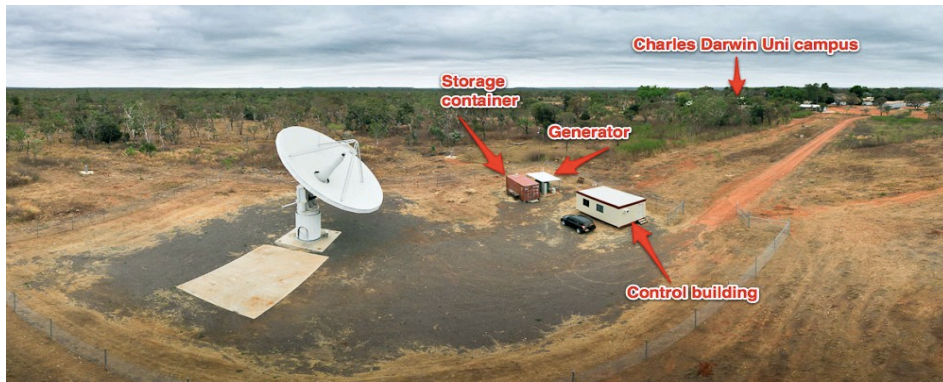


# Sites: Yg

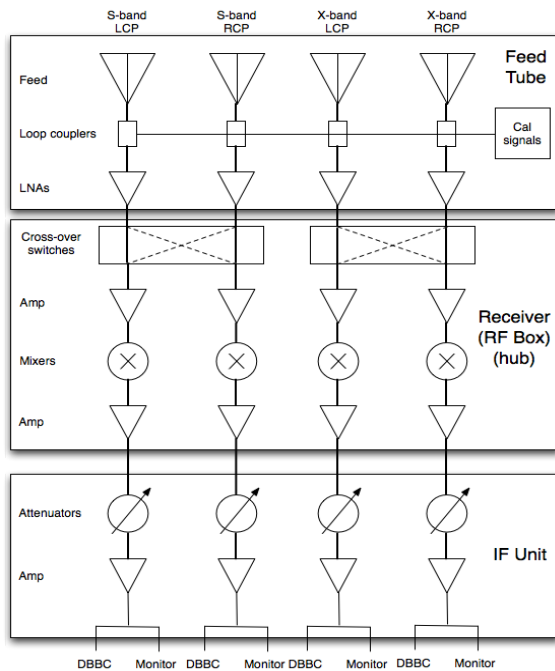
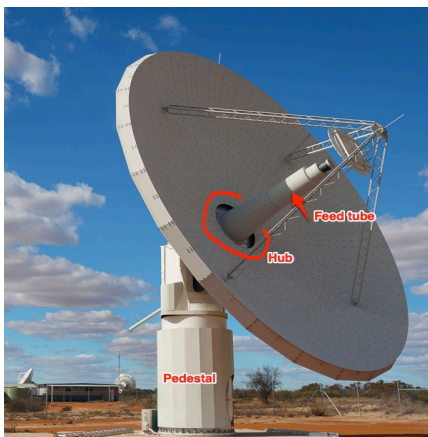


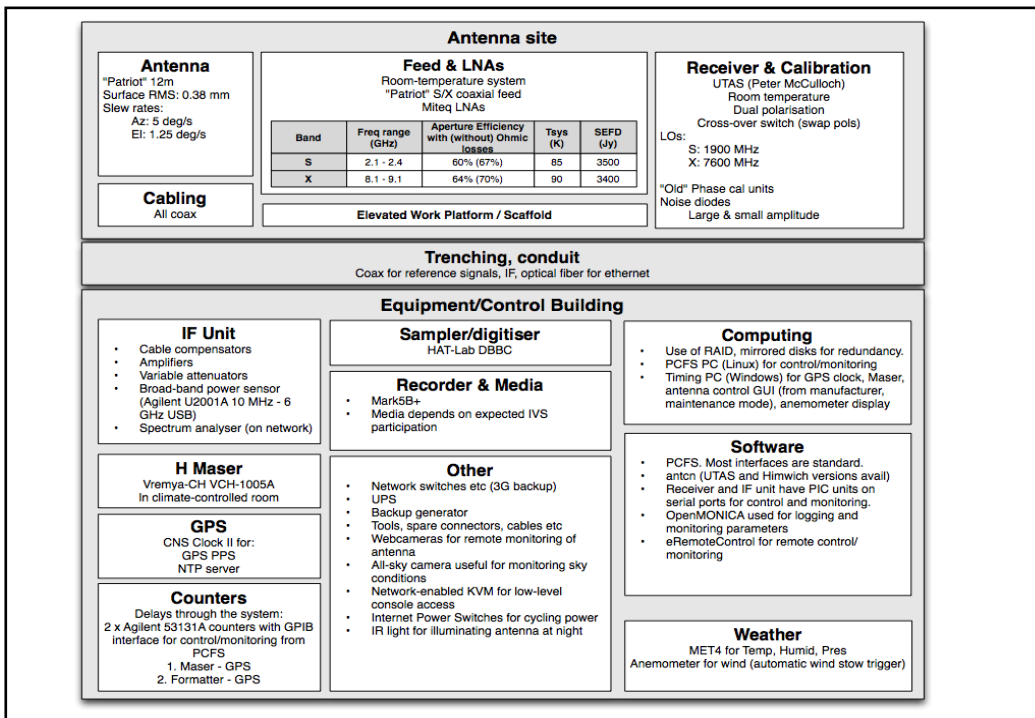
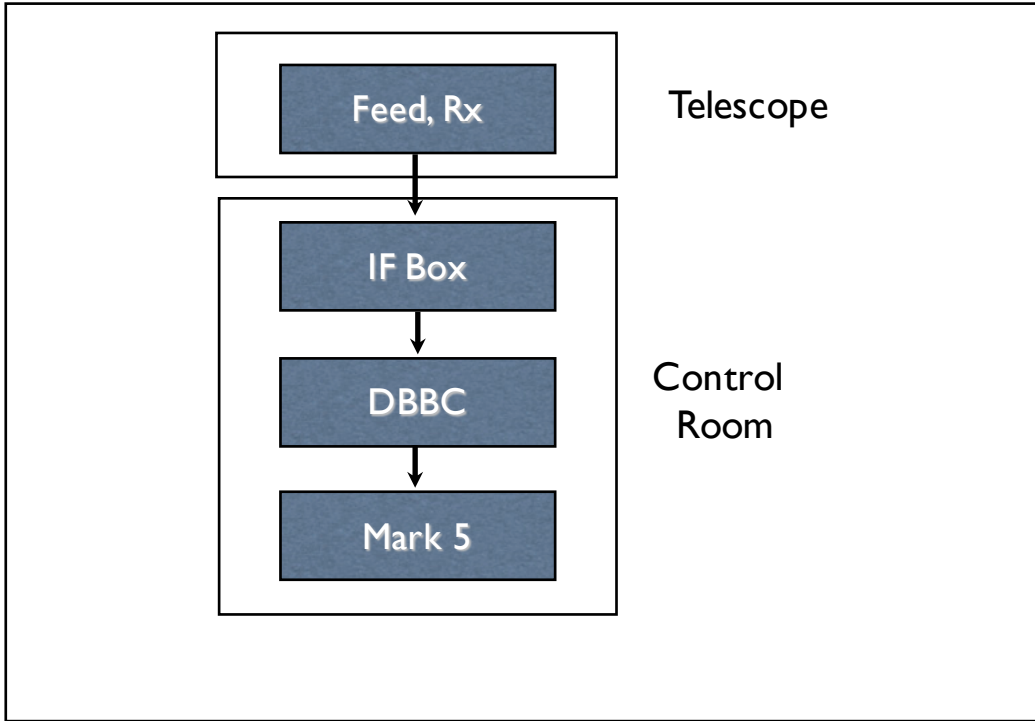
# Sites: Ke

- Co-located with Charles Darwin Uni rural campus, 16km north of Katherine township
- Local contact is Martin Ephgrave



## Signal Path and equipment



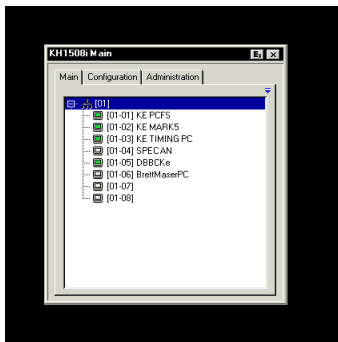


# Network

- Hb: good fiber (AARNET) connection
- Yg:
  - microwave link to nearby town
  - backup 3G connection
- Ke:
  - ~1 Mbps fiber
  - 3G backup

# Networked KVM

Console-level (keyboard, mouse) access over the network.



```

Loading module windows for StreamStor
windows6: no version for "struct_module" found: kernel tainted.
windows6: module license 'Proprietary' taints kernel.
Mandriva 4.6-31 bump (c) 1997 - 2011 Build Date: May 22 2011 x86_32bit 1

Debian GNU/Linux 4.0 mkSke tty1
mkSke login: oper
Password:
Last login: Wed Apr 17 16:56:57 2013 from pcfske.phys.utas.edu.au on pts/1
Linux mkSke 2.6.18-6-686 #1 SMP Fri Feb 19 23:48:03 UTC 2010 i686

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/*copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
oper@mkSke:~$ ACPI: PCI Interrupt 0000:06:02.0(A) -> GSI 27 (level, low) -
90
ACPI: PCI interrupt for device 0000:06:02.0 disabled
PCI: Enabling device 0000:06:02.0 (0158 -> 0153)
ACPI: PCI Interrupt 0000:06:02.0(A) -> GSI 27 (level, low) -> IRQ 90
oper@mkSke:~$

```

# UPS

- Uninterruptible Power Supplies
- Diesel generator

# Internet Power Switch



Western Telematic, Inc. - 1 x

ipske.phys.utas.edu.au/index.htm

News Astro Jim Lovell's Blog Blog Login My Wiki AuScope Ops Wiki Clip to Evernote Meeting Planner - Other Bookmarks

**INTERNET POWER SWITCH**

LOCATION: Katherine Radiotelescope

Firmware Version: 1.41h

SWITCH PANEL		Status	On	Off	Boot	Default
Plug	Name					
1	pc6ike	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
2	mk5ke	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
3	timeke	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
4	windke	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
5	DBBC	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
6	Camera	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
7	ExteriorLight	<span style="color: green;">OFF</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	OFF
8	AgilentUSBHub	<span style="color: green;">ON</span>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	ON
All Plugs			<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>

# Cameras

AuScope VLBI Web Cameras

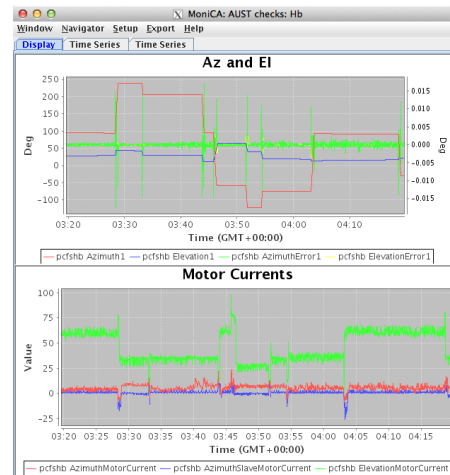
- Webcam web page plus (internal network) live view
- Linux compatibility a good idea

ptzhb

- PTZ (Pan, Tilt, Zoom) camera in control room

# Monitor Points

- Most of the analogue interfaces are provided by PICAXE-based devices which are interfaced to Monica via simple TCP servers.



## Important parts and what they do

- Hydrogen Maser. Ultra-precise time and frequency standard
- GPS clock. Provides UT and comparison with maser PPS (pulse per second)
- RF (Radio Frequency) Unit or Receiver. Down-converts signal from sky frequencies to IF.
- IF (Intermediate Frequency) Unit. Signal conditioning filtering, monitoring, splitting
- DBBC. Digital Base-Band Converter. Analog to Digital stage. Splits signal into 16 x 8 (or 4 or 16) MHz sub-bands and digitises for recording. Also used for measuring Tsys (System Temperature).
- Mark5B+ recorder. Records data from DBBC

# Racks

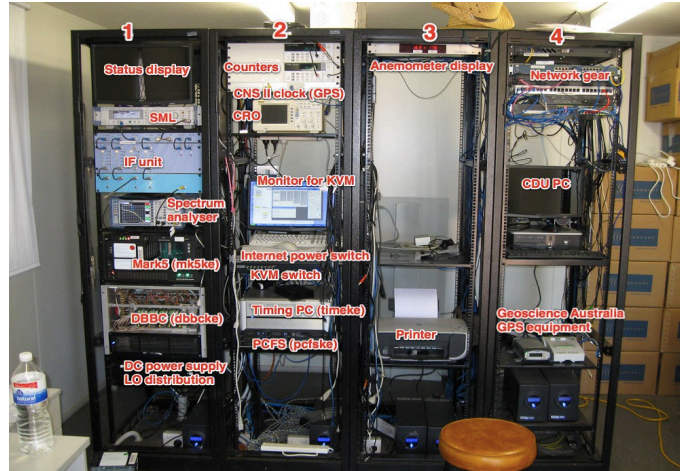
- Numbered the same at Ke, Yg with same equipment in each
- Hb numbered and arranged differently

## Yg racks

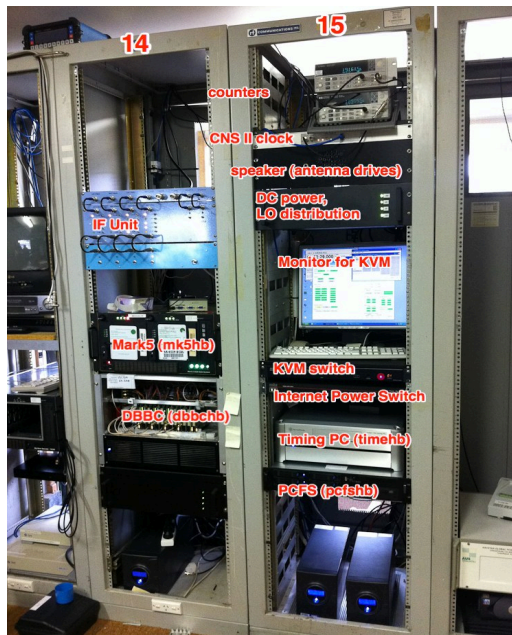




### Ke racks



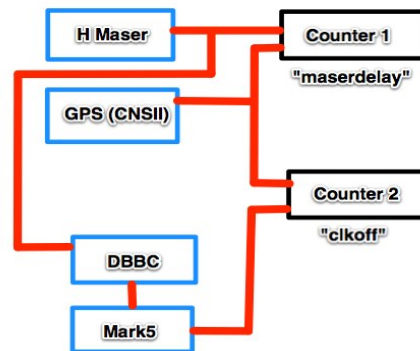
### Hb racks



# Timing

- “maserdelay” measures difference between maser and GPS 1PPS. Used by correlator to find initial solution. A good quick monitor of Maser stability.
- “clkoff” measures delay through signal path. A good diagnostic of DBBC and Mark5 stability.
- Difference between the two should be constant and ~ 0.300 us
- Log monitor calculates the difference and rings an alarm if it detects a problem. Usually the DBBC needs attention.
- The program *finset* is used to synch the Mark5 to the 1PPS from the DBBC. This should only be needed once during setup unless there's a timing problem (DBBC failure, clock jump). Avoid re-synching after a start unless the delay is unstable or gets too big (few us).
- Note, in PCFS, “formatter” = “Mark5”.

## 1 PPS distribution



# Computers

Type	Function	Computer Name			Access with...
		Hobart	Katherine	Yarragadee	
PC Field System	Linux PC that runs Field System software to control the antenna, DBBC and Mark5	pcfshb	pcfске	pcfsg	ssh, VNC (display 1)
Mark5	A Linux PC inside the Mark5 recorder which runs dimino, a program the PCFS communicates with to control data recording	mk5hb	mk5ke	mk5yg	ssh
Timing PC	Windows PC that monitors the H maser, the CNS-II GPS clock, shows the wind speed and direction, and runs HMT: a GUI for controlling and monitoring the antenna	timehb	timeke	timeyg	VNC display 0
DBBC	A Windows PC in the DBBC which runs a server (and optionally a client) program to allow control and monitoring of the DBBC	dbbchb	dbbcke	dbbcyg	VNC display 0

- User account is “observer” on all PCs except pcfс and mk5 where it’s “oper” and DBBC where user = dbbc, password =
- Password is the same everywhere except the DBBC :
- Root password is:
- Other accounts:
  - Telescope webcam: webcamXX : observer : standard
  - Control room cameras: ptzXX : admin : standard
  - Internet Power Switches : ipsXX : admin : root password
  - KVM switches (java client) : kvmXX : administrator : standard
- Proxy. Use your UTAS account or user=jamiesl, password=

# Software

- Central repository of software on a server in Operations Room.
- We use Git for software distribution, version control

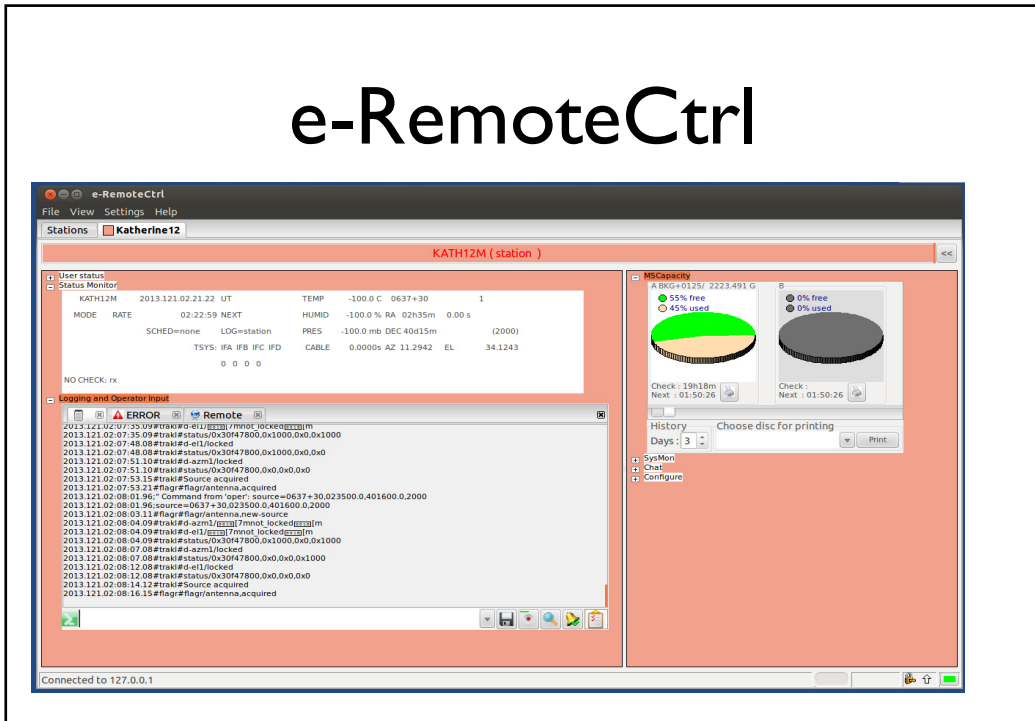
# VNC

The screenshot displays a VNC remote session of a satellite control software. The main window shows various operational parameters and controls:

- POWER STATUS:** Includes buttons for 'READ', 'WRITE', 'REMOTE A/D CAL', 'POWER', 'DRIVES OFF', and 'DRIVES ON'.
- CURRENT POSITION:** Displays 'AZIMUTH' at 0.9993 and 'ELEVATION' at 87.9851.
- CURRENT VIRTUAL AXES VALUES:** A table showing various axes and their values.
- Spectrum Analyser:** A window showing a frequency plot with parameters: RBW 2 MHz, VBW 10 MHz, Span 2.0 GHz, and a peak level of -56.21 dBm.

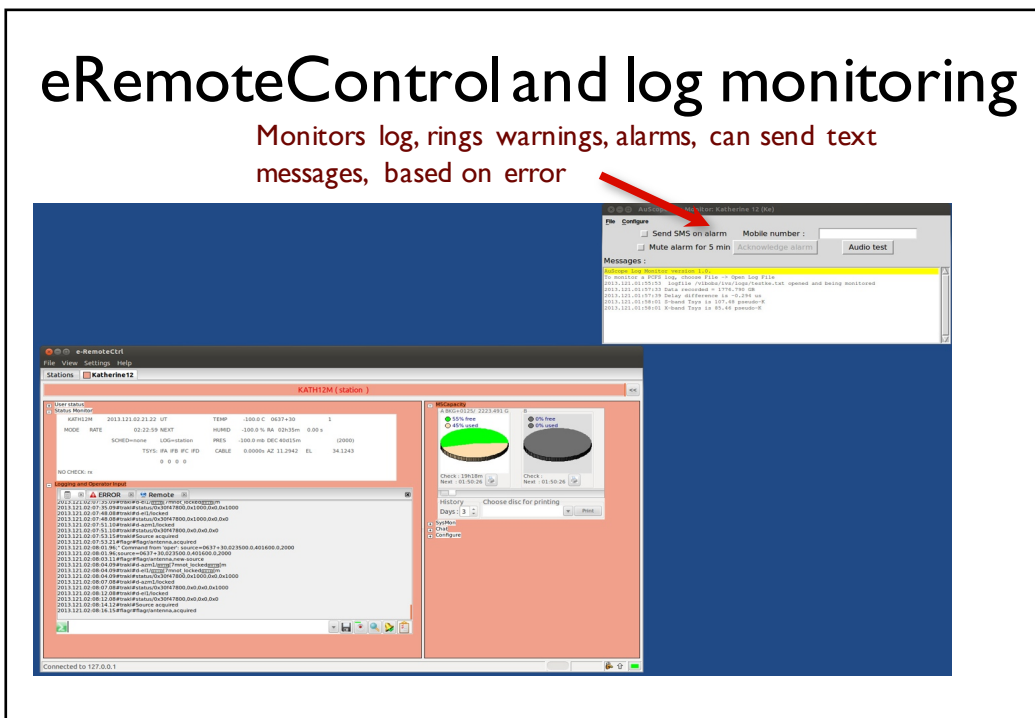
- Timing
- DBBC
- PCFS
- Spectrum analyser

# e-RemoteCtrl

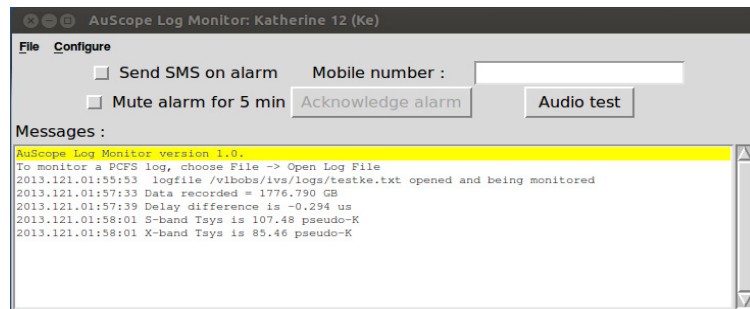


## eRemoteControl and log monitoring

Monitors log, rings warnings, alarms, can send text messages, based on error

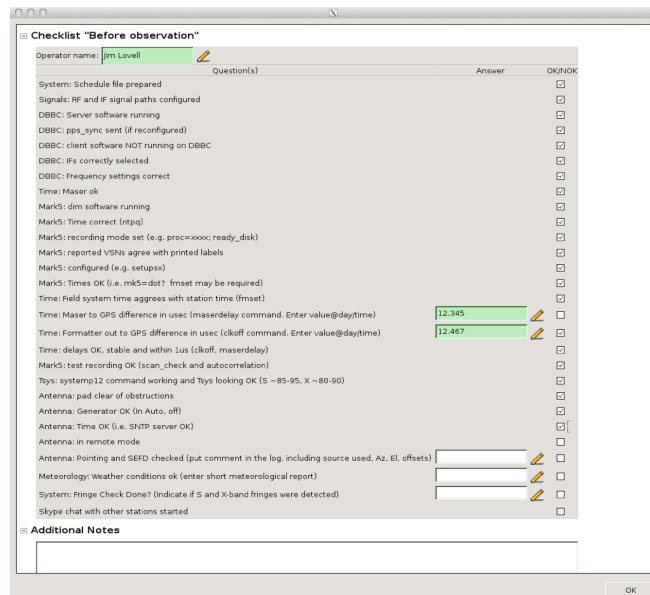


# Log monitor





# Checklists

- Part of e-RemoteCtrl
- One per station, configurable



**Checklist "During observation"**

Operator name:  

Question(s)	Answer	OK/NOK
Antenna: drives OK		<input checked="" type="checkbox"/>
Antenna: Time OK (i.e. SNTP server OK)		<input checked="" type="checkbox"/>
Antenna : on source and tracking		<input checked="" type="checkbox"/>
Data: LO Locked		<input checked="" type="checkbox"/>
Data: Autocorrelations OK		<input checked="" type="checkbox"/>
Time: delays OK, stable and within 1us (clkoff, maserdelay)		<input checked="" type="checkbox"/>
Time: Maser status OK		<input checked="" type="checkbox"/>
Time: Field System time (econtrol StatusMonitor) agrees with station time		<input checked="" type="checkbox"/>
Mark5: mk5=mode? correct		<input checked="" type="checkbox"/>
Mark5: mk5=dot? response nominal		<input checked="" type="checkbox"/>
Mark5: disk_pos OK		<input checked="" type="checkbox"/>
Meteorology: Weather (wth) being logged		<input checked="" type="checkbox"/>
Meteorology: Sky conditions logged (percentage cloud cover, rain etc)	<input type="text" value="clear"/> 	<input checked="" type="checkbox"/>
Tsys: S-band Tsys OK (~85-100)		<input checked="" type="checkbox"/>
Tsys: X-band Tsys OK (~80-95)		<input checked="" type="checkbox"/>
System: Any problems or concerns logged		<input type="checkbox"/>

**Additional Notes**

**Checklist "After observation"**

Operator name:

Question(s)	Answer	OK/NOK
Antenna: back in stow position		<input type="checkbox"/>
Log files processed		<input type="checkbox"/>
Finish email sent		<input type="checkbox"/>

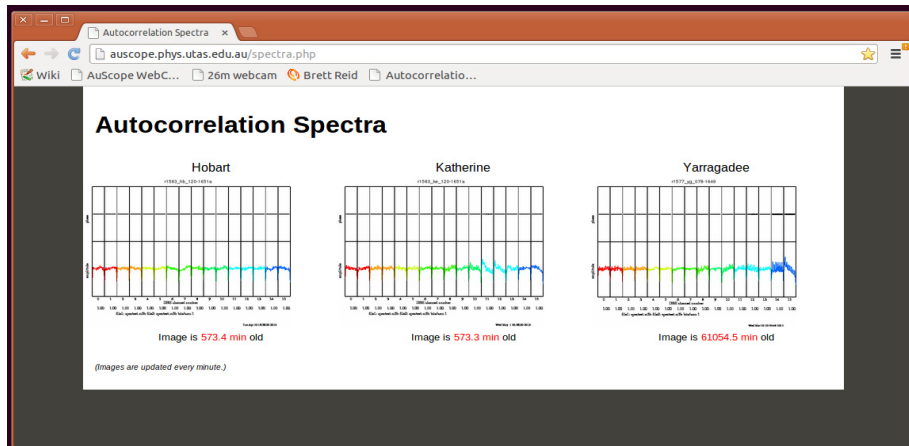
**Additional Notes**

# System Monitor

- One-page summary based on MONICA data

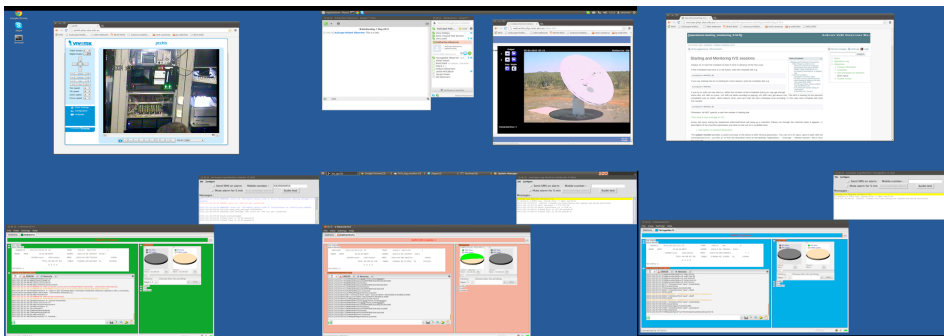
This system monitor uses data from the Monica server

# Autocorrelation plots



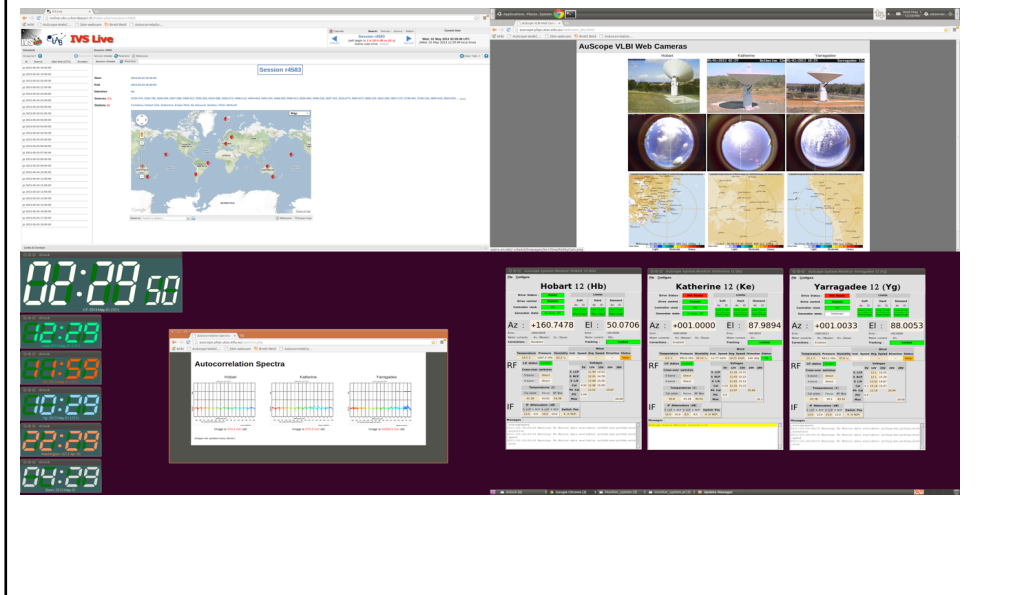
- 1 sec of data autocorrelation after every scan, sent to web server. Good DBBC diagnostic. Can also extract bit statistics

# Operator's desktop





# Monitor screens



# Sequence of events

1. Before an observation
  1. Retrieve and prepare schedule files
  2. Configure and check hardware, run a fringe check
  3. Start the observation
2. During the observation
  1. Regular checks, at least every 2 h
  2. Respond to warnings, alarms
3. After the observation
  1. Prepare and send log files
  2. Ship/e-transfer data (sometimes)
  3. If another observation is to follow, go to 1.1

# Setup procedure

- Schedule and Procedure Files
  - script slogita.uscope.sh on ops-serv2 to grab .skd file, drudg
  - edit .prc file to check DBBC settings
- Check all local software is running (including FS, Dimino, DBBC server) via VNC
- Start system monitor
- Start e-RemoteCtrl
- Start log monitor
- Step through pre-observation checklist in e-RemoteCtrl:
  - RF/IF Signal path
  - DBBC setup
  - Maser check
  - Mark5B setup
  - Clock checks (maser-GPS fmout-GPS)
  - Test recording
  - Tsys/SEFD check
  - Antenna check
  - Weather check
  - Fringe check
- Start observations

# You should be able to

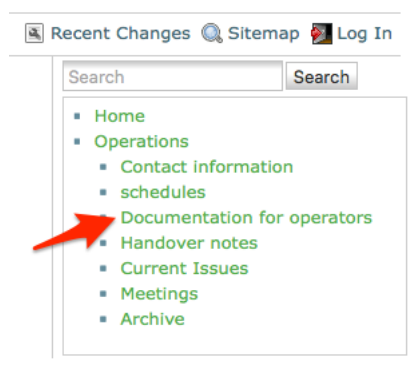
- Start up an observation from scratch
- Run through the checklist
- Know how to fix common problems
- Finish off, process logs
- Not fear the wiki

## Before observing solo

- Observatory visit
- At least one setup
- At least one shift with an experienced observer

## Example setup procedure

# Step-by-step guide on the wiki



In 3 months time,  
you should be able to answer questions  
that demonstrate you understand the  
system. Questions like...

- What does the DBBC do?
- What does fmset do? When should you run it?
- Describe what the Field System does and how eRemoteControl interacts with it
- What is a fringe check and why is it useful?
- What is System Temperature? What is SEFD?
- What do the two counters measure and why do we monitor their output?